

# Engineering Notes

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## Rate of Climb for Light Propeller Powered Airplanes

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WHILE carrying out additional calculations for rates of climb of light airplanes from the equations given in Refs 1 and 2, two mistakes were discovered in our previous paper.<sup>2</sup> A typing error had transposed the last two numbers given for  $\tau$  in Fig 1 of Ref 2, so it should be changed to  $\tau = 0.2278$  in order to provide at least three digit accuracy. A more serious error was found in our calculation of  $w = (dh/dt)_{\max}$  from Eq (13) in Fig 2 of Ref 2. This curve was supposed to represent the maximum climb rate for a fixed pitch propeller that satisfied Oswald's<sup>3</sup> suggestion that the maximum available power should be absorbed at the maximum possible level flight velocity near sea level ( $\sigma = 1 = \phi$ ). Unfortunately, in the calculations from the correctly printed Eq (13) in Ref 2, the first factor was erroneously used as  $\frac{2}{3}(\tau)$ . A recalculation of  $w$  is shown in Fig 1, which replaces Fig 2 of Ref 2, and it is seen that the curve for  $w$  is now more nearly linear and is now properly below the curves for Eqs (14) and (15) which give the rate of climb ( $h$ ) for the ideal variable pitch propeller.

In agreement with the data for most light airplanes the decrease in rate of climb  $w$  with altitude  $h$  is very linear: a straight line from  $(w)_{\sigma=1}$  at  $h = 0$  to  $h_{\text{abs}}$  when  $w = 0$  overestimates the rate of climb by less than 5% at  $h/h_{\text{abs}} = \frac{1}{2}$  and is given by

$$\frac{(dh/dt)_{\max}}{(V^*)_{\sigma=1}} = \frac{w}{(\lambda_p \lambda_s)^{1/4}} = 0.1267 \left( 1 - \frac{h}{h_{\text{abs}}} \right) \quad (1)$$

The absolute ceiling ( $h_{\text{abs}}$ ) is determined from Eq (6) of Ref 2 by the value of  $\sigma = \rho/\rho_0$  as

$$\sigma h = C + \phi_h (1 - C) \quad \text{where } 0 \leq C \leq 0.22 \quad (2)$$

The origin and the selection of the constant  $C$  is discussed in Ref 1. The classical time to climb for light airplanes with a negligible change in weight due to fuel consumption can be obtained by integrating Eq (1) so as to obtain (e.g., see McCormick<sup>4</sup>, pp 439-440):

$$t = \frac{h_{\text{abs}}}{w_{\sigma=1}} \ln \left( 1 - \frac{h}{h_{\text{abs}}} \right)^{-1} \quad (3)$$

From Eq (13) of Ref 2, or Fig 1 above, we have  $w_{\sigma=1} = 4.841 \text{ m/s} = 15.88 \text{ ft/s} = 953 \text{ fpm}$  for the fixed pitch

propeller defined in Ref 2. The so called 'service ceiling' is defined as the altitude ( $h_{\text{ser}}$ ) where the rate of climb is reduced to  $w_{\text{ser}} = 100 \text{ fpm} = 0.508 \text{ m/s}$ . For this Oswald<sup>3</sup> type fixed pitch propeller we can calculate from  $\phi_h = 0.4585$  the absolute ceiling and the time (min) to climb to the service ceiling, both dependent upon the selected constant  $C$  in Eq (2) as

$$C = 0.15; \sigma_h = 0.5397; h_{\text{abs}} = 5980 \text{ m} (19,620 \text{ ft})$$

$$= h_{\text{ser}}/0.895; t = 46.4 \text{ min}$$

$$C = 0.21; \sigma_h = 0.5722; h_{\text{abs}} = 5450 \text{ m} (17,880 \text{ ft})$$

$$= h_{\text{ser}}/0.895; t = 42.3 \text{ min}$$

The constant  $C$  is a correction for the altitude effect upon  $\phi\tau W$  in Ref 2. Quite often this term is simplified to  $\sigma\tau W$  corresponding to  $C = 0$ ; however as shown in Refs 1 and 2, this leads to an overestimation of the maximum velocity and the climb rate at the higher altitudes. It is important to note that even though  $\phi\tau W$  is always less than the static thrust at  $V = 0$  still the basic assumption is that at any given altitude  $\phi\tau W$  is a constant that must be independent of a slowly varying velocity at least in the range  $V_* \leq V \leq V_{\max}$ . As long as this is true Eqs (7) (12) (13), and (16) of Ref 2 provide a good approximation for a fixed pitch propeller whose theoretical thrust variation has been shown to be given by Eq (3) of Ref 2, or Eq (10) of Ref 1. The correction term  $\phi = (\sigma - c)/(1 - c)$  is only a crude approximation to the decrease in thrust with altitude. A much better approximation to  $\phi(h)$  can be obtained by plotting the calculated or experimental fixed pitch propeller thrust versus velocity and then using a "best fit" parabola in the range  $V_* \leq V \leq V_{\max}$  to approximate Eq (3) of Ref 2. It should be noted that the second term  $-(\sigma/2)(P_m/WV_m)(V/V_m)^2$  comes directly from fixed pitch propeller theory where  $V_m$  is the velocity where the engine propeller combination produces its peak power ( $P_m$ ). In any final detailed analysis the engine propeller combination must be considered as the best design compromise providing the desired power available ( $TV$ ).

The curve representing Eq (13) of Ref 2 in Fig 1 is for  $w = (dh/dt)_{\max}$  for a climb with a fixed pitch propeller that has a sufficiently coarse (i.e. high) pitch angle so as to absorb the maximum available power at the maximum level flight speed near sea level ( $\sigma = 1 = \phi$ ). For the airplane considered in Ref 2 this corresponds to  $V_m = V_{\max} = 69.54 \text{ m/s} = 228.15 \text{ ft/s}$ ,  $\tau = 0.2278$  and  $\nu^{-1} = 1.57 \times 10^{-5} \text{ (s/m)}^2 = 1.459 \times 10^6 \text{ (s/ft)}^2$ . As shown in Refs 1 and 2 the rate of climb near sea level can be approximately doubled if a fixed pitch propeller is selected with a sufficiently fine (i.e. low) pitch angle so that at  $\sigma = 1 = \phi$  the maximum available power is absorbed at  $V_m = V_* = 38.2 \text{ m/s} = 125.3 \text{ ft/s}$ . For this case Eq (4) of Ref 2 yields  $\tau_* = 0.4147$  and  $\nu_*^{-1} = 9.471 \times 10^{-5} \text{ (s/m)}^2 = 8.799 \times 10^{-6} \text{ (s/ft)}^2$  so that the sea level rate of climb from Eq (13) of Ref 2 becomes  $w = 7.47 \text{ m/s} = 24.51 \text{ ft/s} = 1470 \text{ fpm}$  at a trim speed of  $V_w = 35.4 \text{ m/s} = 116.1 \text{ ft/s}$ . This corresponds to a trim lift coefficient of  $C_{L_w} = 0.833$  at  $\sigma = 1 = \phi$  which is 17% greater than the lift coefficient for minimum drag  $C_{L_*} = 0.714$  so that this airplane's climb is in the unstable speed range. As shown in Houghton and Carruthers<sup>5</sup> any flight speed less than that for minimum drag ( $V_*$ ) is inherently speed unstable and requires constant corrections

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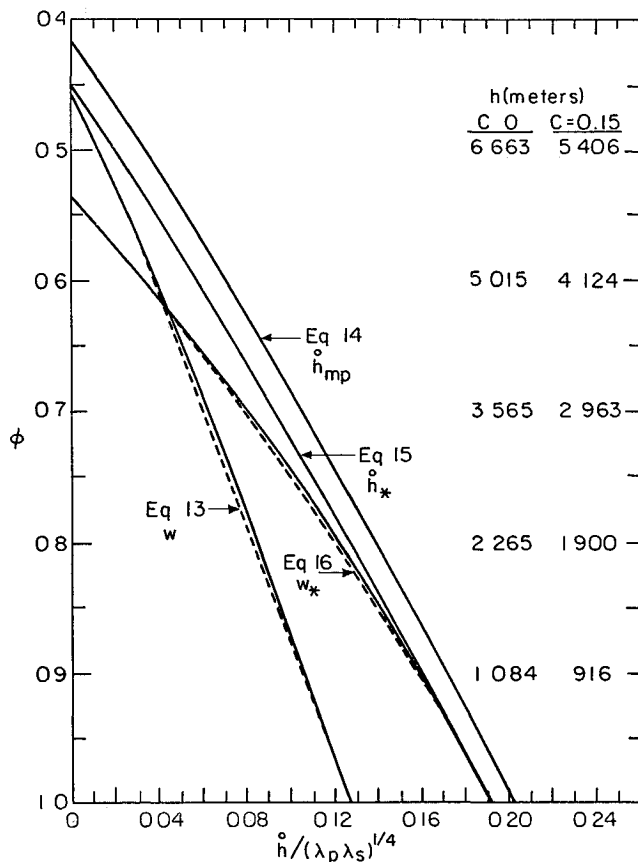


Fig 1 Corrected Fig 2 of Ref 2 Curve for  $w$  from Eq (13) of Ref 2 for a fixed pitch propeller with  $V_m = V_{\max}$  was incorrect. The solid lines are for  $C=0$  and the dotted lines are for  $C=0.15$  ( $\lambda_p \lambda_s)^{1/4} = (V_*)_{\sigma=1} = 38.2 \text{ m/s} = 125.3 \text{ ft/s}$

by the pilot because any speed reduction now results in an increase in drag which slows the airplane even further. In addition, this finer pitch propeller having  $V_m = V_*$  for Eq (13) predicts an absolute ceiling from Eqs (5) and (6) of Ref 2 as  $\phi_h = 0.42$ ;  $V_h = 41 \text{ m/s} = 134.5 \text{ ft/s}$ ; and  $C_{L_h} = 1.48$  which is obviously impossible. Therefore, the proposed operation for this finer pitch propeller was given by Eq (16) of Ref 2 and is shown above as well as in Fig. 2 of Ref 2 as one which restricts the climb to  $C_L = 0.7141$  at a trim speed of  $V_*$  now corresponding to the maximum lift to drag ratio. This finer pitch propeller should provide a quicker takeoff run since

$\tau_* = 0.4147 = 1.82 \tau$  where  $\tau = 0.2278$  for the coarser pitch propeller having  $V_m = V_{\max}$  for peak power. Although the first term  $\tau W$  in Eq (3) of Ref 2 is always less than the actual static thrust, the above calculations indicate the static thrust should be considerably greater for the finer pitch propeller; of course, its maximum level flight speed must be less. From Eq (7) of Ref 2 we calculate  $V_{\max} = 56.6 \text{ m/s} = 185.7 \text{ ft/s}$  near sea level ( $\sigma = 1 = \phi$ ) which is 23% less than that of the coarser pitch propeller. The altitude prediction from Eq (16) is also more reasonable than that from Eq (13) for this finer pitch propeller since  $C_{L_h} = C_L = 0.7141$  is independent of  $C$  and Eq (6) of Ref 2 gives a reasonable value of  $\phi_h = 0.5359 = (\sigma_h - c) / (1 - c)$  so that for  $C = 0.073$  we have  $\sigma_h = 0.57$  and  $h_{\text{abs}} = 5500 \text{ m} = 18000 \text{ ft}$ .

Finally, it should be noted that although Eq (13) of Ref 2 does provide a good approximation for the coarser pitch Oswald<sup>3</sup> type propeller still for the higher altitudes Fig 1 shows that for  $\phi < 0.62$  ( $h/h_{\text{abs}} > 0.65$ )  $w > w_*$  since  $C_{L_w} > C_L$ ; still  $C_{L_w}$  does not become too large for the drag polar approximation since  $C_{L_h} = 0.888 < 1$  is independent of  $C$ . However, the climb at these higher altitudes requires constant pilot attention because of the inherent speed drag instability previously mentioned. Likewise, the climb with a variable pitch propeller is more stable and more likely to be attained by Eq (15) in Ref 2 (see Fig 2 of Ref 2 or Fig 1 above) with climb at a constant  $C_{L_*}$  rather than by Eq (14) with climb at a constant  $C_{L_{mp}} = \sqrt{3} C_L = 1.24 > 1$ . Not only is the latter climb uncomfortably speed drag unstable but for this airplane the predicted rate of climb cannot be attained since as shown in Fig. 1 of Ref 1 the actual drag is 10% greater than that predicted by the drag polar approximation because  $C_{L_{mp}} = 1.24 > 1$ .

The final conclusion of our calculations is that one should climb or glide at a trim speed slightly greater than  $V_*$  in any conventional light airplane as long as  $C_L < 1$ .

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